

## Scope and Sequence for Robotics: Grade 3

### Programming and Building

#### Unit: At-Your-Service Bots

Students use wheel rotations and sensors for navigation and build arms to give their NXT robots the ability to serve food in a restaurant and assist the Forest Service in the dangerous job of fighting fires.

GRADE 3	LEARNER'S PERMIT	OPERATOR'S LICENSE	MISSION POINTS	ROBOTICS ENGINEER
<p><b>At-Your-Service Bots!</b></p>	<p><b>Programming concepts:</b></p> <ul style="list-style-type: none"> <li>Distance can be measured to the nearest tenth or hundredth of a rotation.</li> <li>Turns can be described as clock times (i.e., 3:00 and 9:00 for 90° turns; 6:00 for 180°.</li> <li>A 1:00 turn takes .4 rotations.</li> </ul> <p><b>Tasks to complete:</b></p> <ul style="list-style-type: none"> <li>2-5 step programs with one or more turns.</li> </ul>	<p><b>Programming concepts:</b></p> <ul style="list-style-type: none"> <li>Sensors allow the robot to respond to different conditions (i.e., light or dark, touch sensor in or out).</li> <li>Sensors are wait for commands; they must be used with a move command set for “unlimited.”</li> <li>The sensor sequence must tell the robot what to do when the condition is met (i.e., stop).</li> <li>The “stop” setting on the move command stops the power to the motors.</li> </ul> <p><b>Building concepts:</b></p> <ul style="list-style-type: none"> <li>The NXT light sensor measures reflected light.</li> <li>The touch sensor has two states - in and out.</li> </ul> <p><b>Tasks to complete:</b></p> <ul style="list-style-type: none"> <li>Programs with light, touch, and ultrasonic sensor control.</li> </ul>	<p><b>Programming concepts:</b></p> <ul style="list-style-type: none"> <li>A loop repeats commands.</li> <li>A loop can be set for different conditions.</li> <li>A program can have two strings for simultaneous non-conflicting actions.</li> </ul> <p><b>Building concepts:</b></p> <ul style="list-style-type: none"> <li>Engineers design to meet criteria.</li> <li>Arms should be light, sturdy, and make the best use of parts.</li> </ul> <p><b>Tasks to complete:</b></p> <ul style="list-style-type: none"> <li>Build arms and use sensors to navigate into position to wait tables and serve pizza and soup.</li> </ul>	<p><b>Independent programming and engineering challenges:</b></p> <ul style="list-style-type: none"> <li>Design and build attachments to help assist the Forest Service in the dangerous job of fighting fires.</li> <li>Program a fast and accurate route to meet the challenges.</li> </ul>

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### Academic Content, Deep Learning Proficiencies, and Ed Tech Standards

The eight-week Robotics unit provides students with the opportunity to apply STEM (Science, Technology, Engineering and Math) concepts and skills and develop and practice CFSD’s Deep Learning Proficiencies required of 21<sup>st</sup> Century learners. Students work collaboratively and think critically and creatively in planning, testing, and refining programs; solving problems; and accomplishing engineering tasks.

GRADE 3	MATHEMATICS	SCIENCE	DEEP LEARNING PROFICIENCIES	EDUCATIONAL TECHNOLOGY
<p><b>At-Your-Service Bots!</b></p>	<p><b>Number and Operations - Fractions:</b></p> <ul style="list-style-type: none"> <li>• 3.NF.1. Understand a fraction <math>1/b</math> as the quantity formed by 1 part when a whole is partitioned into <math>b</math> equal parts; understand a fraction <math>a/b</math> as the quantity formed by <math>a</math> parts of size <math>1/b</math>.</li> <li>• 3.NF.2. Understand a fraction as a number on the number line; represent fractions on a number line diagram.</li> </ul> <p><b>Measurement and Data:</b></p> <ul style="list-style-type: none"> <li>• 3.MD.4. Generate measurement data by measuring lengths using rulers marked with halves and fourths of an inch. Show the data by making a line plot, where the horizontal scale is marked off in appropriate units— whole numbers, halves, or quarters.</li> </ul> <p><b>Mathematical Practices:</b></p> <ul style="list-style-type: none"> <li>• 2.MP.5. Use appropriate tools strategically.</li> <li>• 2.MP.6. Attend to precision.</li> </ul>	<p><b>Scientific Inquiry:</b></p> <ul style="list-style-type: none"> <li>• SC3.1d.2 Solves problems using appropriate tools and units of measure.</li> </ul> <p><b>Interaction of Science and Society:</b></p> <ul style="list-style-type: none"> <li>• SC3.2. Describes the development and use of different technologies in response to resources, needs, and values.</li> </ul>	<p><b>Collaboration:</b></p> <ul style="list-style-type: none"> <li>▪ Fulfills various basic roles and responsibilities in order to complete a task.</li> <li>▪ Uses strategies to respectfully resolve conflicts with another team member.</li> <li>▪ Completes individual action items to achieve the team goals.</li> <li>▪ Submits products that meet the specifications for the group tasks.</li> <li>▪ Acts upon feedback that suggests changes or revisions to work, based upon provided criteria for success.</li> </ul> <p><b>Critical Thinking and Problem Solving:</b></p> <ul style="list-style-type: none"> <li>• Uses established criteria to identify errors in the thinking or problem-solving process.</li> </ul> <p><b>Creativity and Innovation:</b></p> <ul style="list-style-type: none"> <li>• Discards ideas or solutions if viability is not confirmed; modifies an idea or solution in response to constructive criticism or failure.</li> <li>• Integrates ideas from others with own ideas in order to address the problem or task.</li> <li>• Selects materials that are appropriate to the product or</li> </ul>	<p><b>Technology Operations and Concepts:</b></p> <ul style="list-style-type: none"> <li>• ET3.6.14 Transfers understanding of current input/output devices and symbols and icons to learning new technologies.</li> </ul>

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			<p>solution.</p> <ul style="list-style-type: none"><li>• Creates and follows a general plan to meet the specification of the product or solution.</li><li>• Assesses the quality of the performance and creative process in response to feedback and/or established criteria.</li></ul>	